

TAA-308 TAA-315 TAA-340

Navigation-grade MEMS Accelerometers





TAA-308



TAA-340

Weighs

Accelerometers Bias in-run stability Accelerometers Bias error over temperature range Accelerometers Bias One Year repeatability Velocity Random Walk 8 grams 15 grams 40 grams 0.005 mg 0.01 mg 0.02 mg 0.5 mg 0.7 mg 1.2 mg 1 mg 1.3 mg 1.5 mg 0.015 m/sec/\sqrt/hr 0.045 m/sec/\sqrt/hr 0.045 m/sec/\sqrt/hr

TAA-315





TAA-308EC TAA-315EC TAA-340EC

Navigation-grade MEMS Accelerometers







Weighs

Accelerometers Bias in-run stability Accelerometers Bias error over temperature range Accelerometers Bias One Year repeatability Velocity Random Walk

TAA-308EC TAA-315EC

13 grams 13 grams 0.003 mg 0.005 mg 0.2 mg 0.3 mg 0.35 mg 0.45 mg 0.01 m/sec/√hr 0.02 m/sec/√hr

TAA-340EC

13 grams 0.01 mg 0.5 mg 0.55 mg 0.03 m/sec/√hr

TAG-200 TAG-300

Two and Three Axis Gyroscopes





Size	39 x 45 x 22 mm
Weighs	70 grams
Data Update Rate	2000 Hz
Bias in-run stability	2°/hr
Noise (ARW)	





TAG-304

Three Axis Gyroscope



Size	19.5 x 15.2 x 5.5 mm
Weighs	10 grams
Data Update Rate	4000 Hz
Bias in-run stability	
Noise (ARW)	0.02°/√hr

KERNEL-100



Size	. 28.5 x 19.5 x 8.5 mm
Weighs	7 grams
Gyroscopes Bias in-run stability	2°/hr
Accelerometers Bias in-run stability	0.01 mg
Velocity Random Walk	
Pitch & Roll accuracy	0.05°





KERNEL-110 KERNEL-120





Size	28.38 x 19.5 x 10.5 mm
Weighs	10 grams
Gyroscopes Bias in-run stability	2º/hr
Accelerometers Bias in-run stability	0.01 - 1 mg
Velocity Random Walk	0.02 - 15 m/sec/√hr
Pitch & Roll accuracy	0.05°

KERNEL-210 KERNEL-220





Size	. 28.38 x 19.5 x 10.5 mm
Weighs	15-17 grams
Gyroscopes Bias in-run stability	1º/hr
Accelerometers Bias in-run stability	0.005 mg
Velocity Random Walk	
Pitch & Roll accuracy	
Shock	





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Gyroscopes Bias in-run stability	0.5 - 1°/hr
Angular Random Walk	0.06 - 0.2°/√hr
Accelerometers Bias in-run stability	0.005 mg
Velocity Random Walk	0.015 m/sec/√hr
Pitch & Roll accuracy	0.05°

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Gyroscopes Bias in-run stability	0.5 - 1 °/hr
Angular Random Walk	0.06 - 0.2 °∕√hr
Accelerometers Bias in-run stability	0.005 mg
Velocity Random Walk	015 m/sec/√hr
Pitch & Roll accuracy	0.05°





IMU-NAV-100-A IMU-NAV-100-S





Gyroscopes Bias in-run stability	0.5 - 1°/hr
Angular Random Walk	0.04°/√hr
Accelerometers Bias in-run stability	0.003 mg
Velocity Random Walk	0.008 m/sec/ _{\(\sqrt{hr}\)}
Pitch & Roll accuracy	•

IMU-FI-200C



Gyroscopes bias repeatability	0.5°/hr
Gyroscopes noise (ARW)	.0.025°/√hr
Accelerometers Bias in-run stability	0.015 mg
Accelerometers Bias repeatability	
Accelerometers SF accuracy	





AHRS-10B AHRS-10P

Attitude & Heading Reference System



Pitch & Roll accuracy	0.05°
Heading/Azimuth accuracy	. 0.3°
Gyro-compensated Fluxgate compass	
Tactical-grade MEMS IMU	

AHRS-II-P

Attitude & Heading Reference System







MINI-AHRS

Attitude & Heading Reference System



Size53 x 19 x	13 mm
Pitch & Roll accuracy	0.05°
Heading/Azimuth accuracy	0.3°
Gyroscopes Bias in-run stability	2º/hr
Embedded 3D magnetic calibration	
Suitable for Primary Attitude Reference	

OPTOAHRS-II

Opto Attitude & Heading Reference System







CHEETAH NAV

Tactical Inertial Navigation System







Main Display Unit & Driver Display Unit
MEMS tactical grade IMU or FOG IMU

INS-U

GPS-Aided Inertial Navigation System



Heading accuracy	
Pitch & Roll accuracy	0.05°
Position accuracy	1cm
Velocity accuracy	0.05 m/sec
IMU, AHRS, INS, and ADC solution	
Embedded Air Data Computer (ADC)	
Low Position Drift in GPS-denied Environment	





INS-P, B, D GPS-Aided Inertial Navigation System

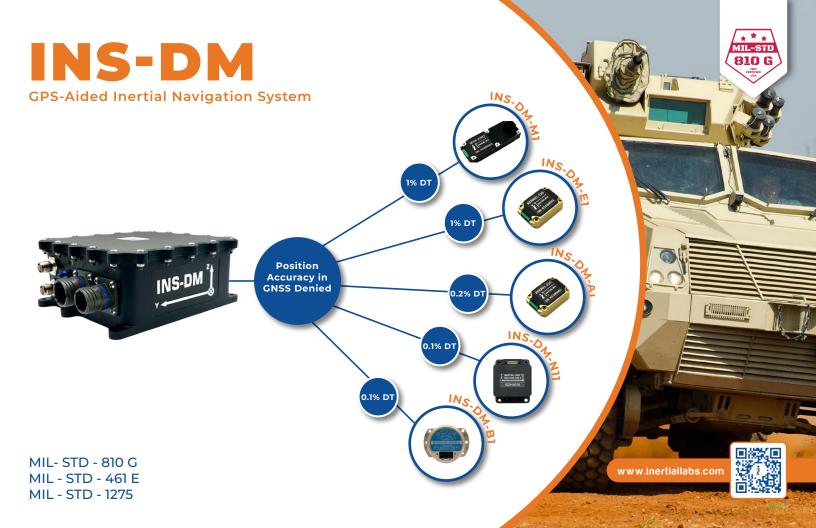








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INS-B, P, D-OEM

GPS-Aided Inertial Navigation Systems



Size	.85.5 x 47.7 x 39.4 mm
RTK Position Accuracy	0.5 - 1 cm
Heading accuracy	0.03°
Pitch & Roll accuracy	0.006°
High precision MEMS IMU	

Novatel, uBlox, Septenrtrio GNSS receiver GPS, GLONASS, Galileo, BeiDou, SBAS, DGPS

INS-DH-OEM

GPS-Aided Inertial Navigation Systems



RTK Position Accuracy1cm	
Heading accuracy	
Pitch & Roll accuracy0.002°	
Honeywell HG4930 IMU	
Novatel, uBlox, Septenrtrio GNSS receiver	
GPS, GLONASS, Galileo, BeiDou, SBAS, DGPS, RTK, PPK, PPP	









Size	73.4 × 55 × 29.5 mm
Weight	130 grams
Pressure Sensor Measurement Range	±25; ±600 mbar
Baro-Corrected Pressure Altitude	500 to 9000 meters
True Airspeed	5 to 64 meters/sec
True Angle of Attack	50° to 50°
Outside Air Temperature (OAT)	40°C to +85 °C

MRU-B1, P, E, PD

Motion Reference Units





Heave, Surge & Sway accuracy	5 cm
Pitch & Roll accuracy	0.02°
Heading accuracy	
NMEA 0183, TSS1 data format	
Compatibility with HYPACK, SBES & MBES	

Solution for: AHC, DP, HMS, Buoys, Survey







WS-E WS-PD

Wave Sensor



Wave Direction Accuracy	1 - 0.5°
Pitch & Roll Accuracy	0.02°
Heading Accuracy0	.05 - 0.06°

MRU-S

Subsea Motion Reference Units











RESEPI LIDAR

Remote Sensing Payload Instrument





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NOTES:



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Inertial Labs Attitude is Everything



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